

Advection of nematic liquid crystals by chaotic flow

Lennon Ó Náraigh

School of Mathematics and Statistics and the Institute for Discovery,
University College Dublin, Ireland

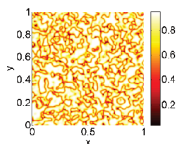
21st November 2016

The Landau–de Gennes Equation

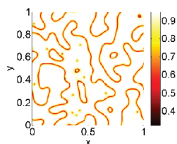
In the absence of flow, the Landau–de Gennes equation governs the orientation dynamics of an ensemble of liquid-crystal molecules:

$$\zeta_1 \frac{\partial \mathbf{Q}}{\partial t} = - \left[\frac{\delta F}{\delta \mathbf{Q}} - \frac{1}{3} \text{tr} \left(\frac{\delta F}{\delta \mathbf{Q}} \right) \mathbb{I} \right]$$

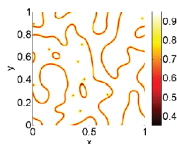
where \mathbf{Q} is the (symmetric, traceless) Q -tensor encoding information about the orientation of the molecules and F is the Landau free energy functional.



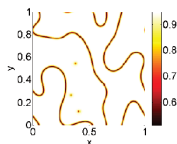
(a) $t = 100$



(b) $t = 1000$



(c) $t = 2000$



(d) $t = 5000$

Shown are snapshots of the scalar order parameter $S = \sqrt{6\text{tr}(\mathbf{Q}^2)}$. The system forms domains – coherent regions where the system relaxes locally to a single (stable) fixed point. The domains grow in time – **coarsening**.

Liquid-crystal dynamics with flow

An appropriate (materially frame-indifferent) model coupling the Q -tensor dynamics to hydrodynamics leads to a model with a highly non-Newtonian form for the stress tensor:

$$\begin{aligned} \text{Q-tensor:} \quad & \zeta_1 \left(\frac{\partial \mathbf{Q}}{\partial t} + \mathbf{v} \cdot \nabla \mathbf{Q} - \boldsymbol{\Omega} \mathbf{Q} - \mathbf{Q} \boldsymbol{\Omega} \right) + \underbrace{\zeta_2 \mathbf{D}}_{\text{Note inhomogeneity!}} = \\ & k \nabla^2 \mathbf{Q} - (\alpha_F \mathbf{Q} - 3\beta_F \mathbf{Q}^2 + 4\gamma_F \text{tr}(\mathbf{Q}^2) \mathbf{Q}) + \frac{1}{3} \mathbb{I} [\zeta_2 \text{tr}(\mathbf{D}) - 3\beta_F \text{tr}(\mathbf{Q}^2)], \end{aligned}$$

$$\text{Hydrodynamics:} \quad \rho_0 \left(\frac{\partial \mathbf{v}}{\partial t} + \mathbf{v} \cdot \nabla \mathbf{v} \right) = \nabla \cdot \mathbf{T},$$

$$\mathbf{T} = -p \mathbb{I} - k \nabla \mathbf{Q} \odot \nabla \mathbf{Q} + \zeta_2 \overset{\circ}{\mathbf{Q}} + \zeta_3 \mathbf{D} + \zeta_{31} (\mathbf{D} \mathbf{Q} + \mathbf{Q} \mathbf{D}) + \zeta_{32} (\mathbf{D} \cdot \mathbf{Q}) \mathbf{Q},$$

$$\text{Incompressibility:} \quad \nabla \cdot \mathbf{v} = 0.$$

Non-dimensional equations – dimensionless groups

Length scale ℓ and timescale $t_0 = \zeta_1/(8\gamma_F)$ – hence dimensionless Q-tensor equation

$$\begin{aligned} \frac{\partial \mathbf{Q}}{\partial \tilde{t}} + \tilde{\mathbf{v}} \cdot \tilde{\nabla} \mathbf{Q} - \tilde{\boldsymbol{\Omega}} \mathbf{Q} - \mathbf{Q} \tilde{\boldsymbol{\Omega}} + \underbrace{\text{Tu}}_{=(\zeta_2/\zeta_1)} \tilde{\mathbf{D}} \\ = \epsilon^2 \tilde{\nabla}^2 \mathbf{Q} + g_1(1-\theta) \mathbf{Q} + 3g_2 \mathbf{Q}^2 - \frac{1}{2} \text{tr}(\mathbf{Q}^2) \mathbf{Q} + \frac{1}{3} \mathbb{I} \left[\text{Tu tr}(\tilde{\mathbf{D}}) - 3g_2 \text{tr}(\mathbf{Q}^2) \right], \end{aligned}$$

where

Non-dimensional equations – dimensionless groups

Length scale ℓ and timescale $t_0 = \zeta_1/(8\gamma_F)$ – hence dimensionless Q-tensor equation

$$\begin{aligned} \frac{\partial \mathbf{Q}}{\partial \tilde{t}} + \tilde{\mathbf{v}} \cdot \tilde{\nabla} \mathbf{Q} - \tilde{\boldsymbol{\Omega}} \mathbf{Q} - \mathbf{Q} \tilde{\boldsymbol{\Omega}} + \underbrace{\mathbf{Tu}}_{=(\zeta_2/\zeta_1)} \tilde{\mathbf{D}} \\ = \epsilon^2 \tilde{\nabla}^2 \mathbf{Q} + g_1(1-\theta) \mathbf{Q} + 3g_2 \mathbf{Q}^2 - \frac{1}{2} \text{tr}(\mathbf{Q}^2) \mathbf{Q} + \frac{1}{3} \mathbb{I} \left[\mathbf{Tu} \text{tr}(\tilde{\mathbf{D}}) - 3g_2 \text{tr}(\mathbf{Q}^2) \right], \end{aligned}$$

where

$$\alpha_F/(8\gamma_F) = -g_1[1 - (T/T_*)] \equiv -g_1(1 - \theta), \quad \beta_F/(8\gamma_F) = g_2, \quad \epsilon^2 = k/(8\ell^2\gamma_F).$$

Non-dimensional equations – dimensionless groups

Length scale ℓ and timescale $t_0 = \zeta_1/(8\gamma_F)$ – hence dimensionless Q-tensor equation

$$\begin{aligned} \frac{\partial \mathbf{Q}}{\partial \tilde{t}} + \tilde{\mathbf{v}} \cdot \tilde{\nabla} \mathbf{Q} - \tilde{\Omega} \mathbf{Q} - \mathbf{Q} \tilde{\Omega} + \underbrace{\mathbf{Tu}}_{=(\zeta_2/\zeta_1)} \tilde{\mathbf{D}} \\ = \epsilon^2 \tilde{\nabla}^2 \mathbf{Q} + g_1(1-\theta) \mathbf{Q} + 3g_2 \mathbf{Q}^2 - \frac{1}{2} \text{tr}(\mathbf{Q}^2) \mathbf{Q} + \frac{1}{3} \mathbb{I} \left[\mathbf{Tu} \text{tr}(\tilde{\mathbf{D}}) - 3g_2 \text{tr}(\mathbf{Q}^2) \right], \end{aligned}$$

where

$$\alpha_F/(8\gamma_F) = -g_1[1 - (T/T_*)] \equiv -g_1(1 - \theta), \quad \beta_F/(8\gamma_F) = g_2, \quad \epsilon^2 = k/(8\ell^2\gamma_F).$$

Hence also, a dimensionless momentum equation:

$$\frac{\partial \tilde{\mathbf{v}}}{\partial \tilde{t}} + \tilde{\mathbf{v}} \cdot \tilde{\nabla} \tilde{\mathbf{v}} = -\tilde{\nabla} \tilde{p} + \frac{1}{\text{Re}} \nabla \cdot \tilde{\mathbf{D}} + \text{Br} \nabla \cdot \left[-\epsilon^2 \tilde{\nabla} \mathbf{Q} \odot \tilde{\nabla} \mathbf{Q} + \dots \right],$$

Non-dimensional equations – dimensionless groups

Length scale ℓ and timescale $t_0 = \zeta_1/(8\gamma_F)$ – hence dimensionless Q-tensor equation

$$\begin{aligned} \frac{\partial \mathbf{Q}}{\partial \tilde{t}} + \tilde{\mathbf{v}} \cdot \tilde{\nabla} \mathbf{Q} - \tilde{\Omega} \mathbf{Q} - \mathbf{Q} \tilde{\Omega} + \underbrace{\text{Tu}}_{=(\zeta_2/\zeta_1)} \tilde{\mathbf{D}} \\ = \epsilon^2 \tilde{\nabla}^2 \mathbf{Q} + g_1(1-\theta) \mathbf{Q} + 3g_2 \mathbf{Q}^2 - \frac{1}{2} \text{tr}(\mathbf{Q}^2) \mathbf{Q} + \frac{1}{3} \mathbb{I} \left[\text{Tu tr}(\tilde{\mathbf{D}}) - 3g_2 \text{tr}(\mathbf{Q}^2) \right], \end{aligned}$$

where

$$\alpha_F/(8\gamma_F) = -g_1[1 - (T/T_*)] \equiv -g_1(1 - \theta), \quad \beta_F/(8\gamma_F) = g_2, \quad \epsilon^2 = k/(8\ell^2\gamma_F).$$

Hence also, a dimensionless momentum equation:

$$\frac{\partial \tilde{\mathbf{v}}}{\partial \tilde{t}} + \tilde{\mathbf{v}} \cdot \tilde{\nabla} \tilde{\mathbf{v}} = -\tilde{\nabla} \tilde{p} + \frac{1}{\text{Re}} \nabla \cdot \tilde{\mathbf{D}} + \text{Br} \nabla \cdot \left[-\epsilon^2 \tilde{\nabla} \mathbf{Q} \odot \tilde{\nabla} \mathbf{Q} + \dots \right],$$

where

$$\text{Br} = \frac{\zeta_1}{\rho_0 \ell (\ell/t_0)}, \quad \text{Re} = \frac{\rho_0 \ell (\ell/t_0)}{\zeta_3}.$$

Limiting case

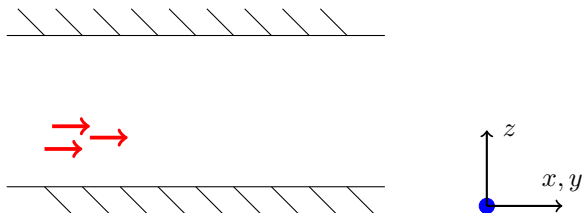
We work on the limit where $\text{Br} = 0$ – no feedback of Q-tensor gradients into the flow – flow is independent of Q-tensor. We can therefore apply **standard chaotic flows** to the Q-tensor dynamics

$$\begin{aligned} \frac{\partial \mathbf{Q}}{\partial \tilde{t}} + \tilde{\mathbf{v}} \cdot \tilde{\nabla} \mathbf{Q} - \tilde{\boldsymbol{\Omega}} \mathbf{Q} - \mathbf{Q} \tilde{\boldsymbol{\Omega}} + \underbrace{\text{Tu}}_{=(\zeta_2/\zeta_1)} \tilde{\mathbf{D}} \\ = \epsilon^2 \tilde{\nabla}^2 \mathbf{Q} + g_1(1 - \theta) \mathbf{Q} + 3g_2 \mathbf{Q}^2 - \frac{1}{2} \text{tr}(\mathbf{Q}^2) \mathbf{Q} + \frac{1}{3} \mathbb{I} \left[\text{Tu} \text{tr}(\tilde{\mathbf{D}}) - 3g_2 \text{tr}(\mathbf{Q}^2) \right], \end{aligned}$$

The **flow timescales** and the **tumbling parameter** Tu are the key parameters.

Two-dimensional geometry

We work with a sample confined between two narrowly separated parallel plates. **Anchoring conditions** are applied in the same fashion at the top and bottom walls such that the director is parallel to the plates.



As such, the Q-tensor simplifies:

$$\mathbf{Q} = \begin{pmatrix} q & r & 0 \\ r & s & 0 \\ 0 & 0 & -(q+s) \end{pmatrix}.$$

Fixed-point analysis

We look at fixed points for $\mathbf{v} = \nabla = \partial_t = 0$. Remarkably, all fixed points can be found in closed form (not shown) and classified:

- Case 1a ($r = 0, s = q$) gives stable and unstable states – **biaxial**
- Case 1b,c ($r = 0, s \neq q$) give neutral and unstable state – **uniaxial**
- Case 2 gives neutral and unstable state – **uniaxial**

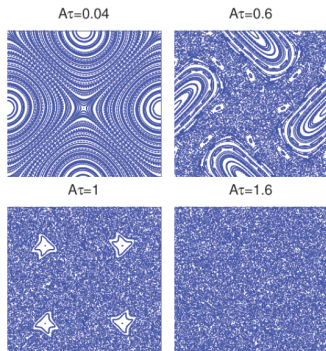
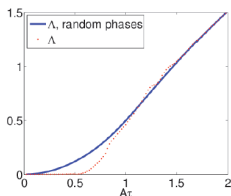
Model sine flow

We use a model (quasi-) periodic velocity field,

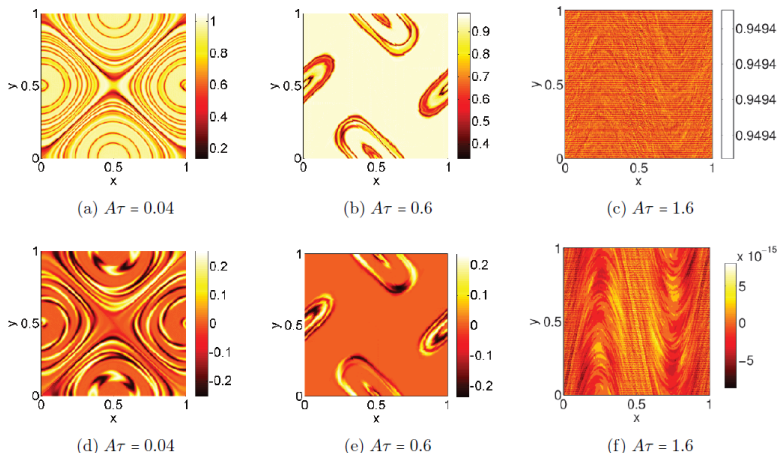
$$\begin{aligned}u &= A \sin(k_0 y + \varphi_n), & 0 \leq \text{mod}(t, \tau) < \frac{1}{2}\tau, \\v &= A \sin(k_0 x + \psi_n), & \frac{1}{2}\tau \leq \text{mod}(t, \tau) < \tau,\end{aligned}$$

which mimics the effect of turbulence at high Prandtl number.

- The phases φ_n and ψ_n are held constant or are randomized periodically.
- The velocity field has a Lagrangian timescale given by the Lyapunov exponent Λ , which can be computed for the constant-phase and random-phase cases.

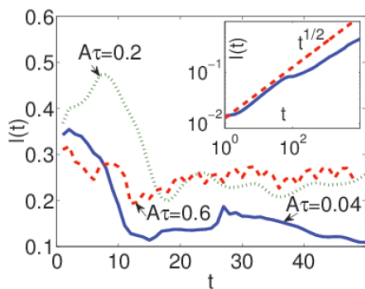


Results – no tumbling, constant-phase sine flow

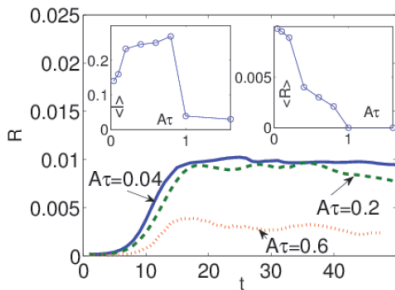


Across the top: snapshots of scalar order parameter at various times for various values of $A\tau$, with $Tu = 0$. Across the bottom: corresponding snapshots of r . Snapshots in the first two columns are taken at $t = 320$. The third column (figures (c) and (f)) concerns $A\tau = 1.6$, for which the snapshots are taken at $t = 320$; these are included here to demonstrate the relaxation to a uniform state for the large values of $A\tau$. The compressed colour bars in these figures is a consequence of the rapid relaxation to the uniform steady state.

Coarsening is arrested / overwhelmed



(a)



(b)

(a) Time evolution of the domain scale $L(t)$ for various values of $A\tau$. The inset shows the time-averaged values of $L(t)$ for a much larger range of $A\tau$ -values, with angle brackets denoting a time average. The time-averages are taken over intervals where the Q -tensor dynamics are in a statistically steady state. (b) The same, for $R := L_x^{-1} L_y^{-1} \iint r^2 dx dy$

Discussion / Conclusions

Stirring by inhomogeneous shear affects orientation of liquid-crystal molecules:

- Low values of τ – domain structures ‘frozen in’ to flow structure.
- High values – domains overwhelmed and everything relaxes to biaxial state.
- Random-phase sine flow – everything is biaxial.
- Understanding depends on studying dynamics along Lagrangian trajectories:

$$\frac{d}{dt} \begin{pmatrix} q \\ r \\ s \end{pmatrix} = \begin{pmatrix} F_1(q, r, s) \\ F_2(q, r, s) \\ F_3(q, r, s) \end{pmatrix} + \begin{pmatrix} 2r\Omega_{12} \\ \Omega_{12}(s - q) \\ -2r\Omega_{12} \end{pmatrix}, \quad \text{Tu} = 0, \quad (\text{Diffusion negligible})$$

- Ongoing work – investigate robustness of results to different model flows
- Future work – Apply known techniques to the reduced planar model:
 - ▶ Bounds and *a priori* estimates
 - ▶ Lubrication theory
 - ▶ DNS of the fully coupled system – **the backreaction will be back!**